

fortiss

Danish-Bavarian Workshop on Robotics/ICT in Horizon 2020



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fortiss

fortiss

Landesforschungsinstitut des Freistaats Bayern
An-Institut Technische Universität München



A brief overview of fortiss

Bavarian research institute with a focus on computer science

Research Institute of the Free State of Bavaria

Affiliated Institute of the Tech. Univ. Munich

Research on methods of

- Software development
- Systems & service engineering
- Robust AI-based solutions
- Reliable, secure cyber-physical systems

Transfer to industry, in particular SMEs

Bavarian Center
for Applied AI

IBM fortiss
Center for AI

DIH Munich
Innovation Hub
for Applied AI



3

offices in Munich



180

employees



60

running
research projects

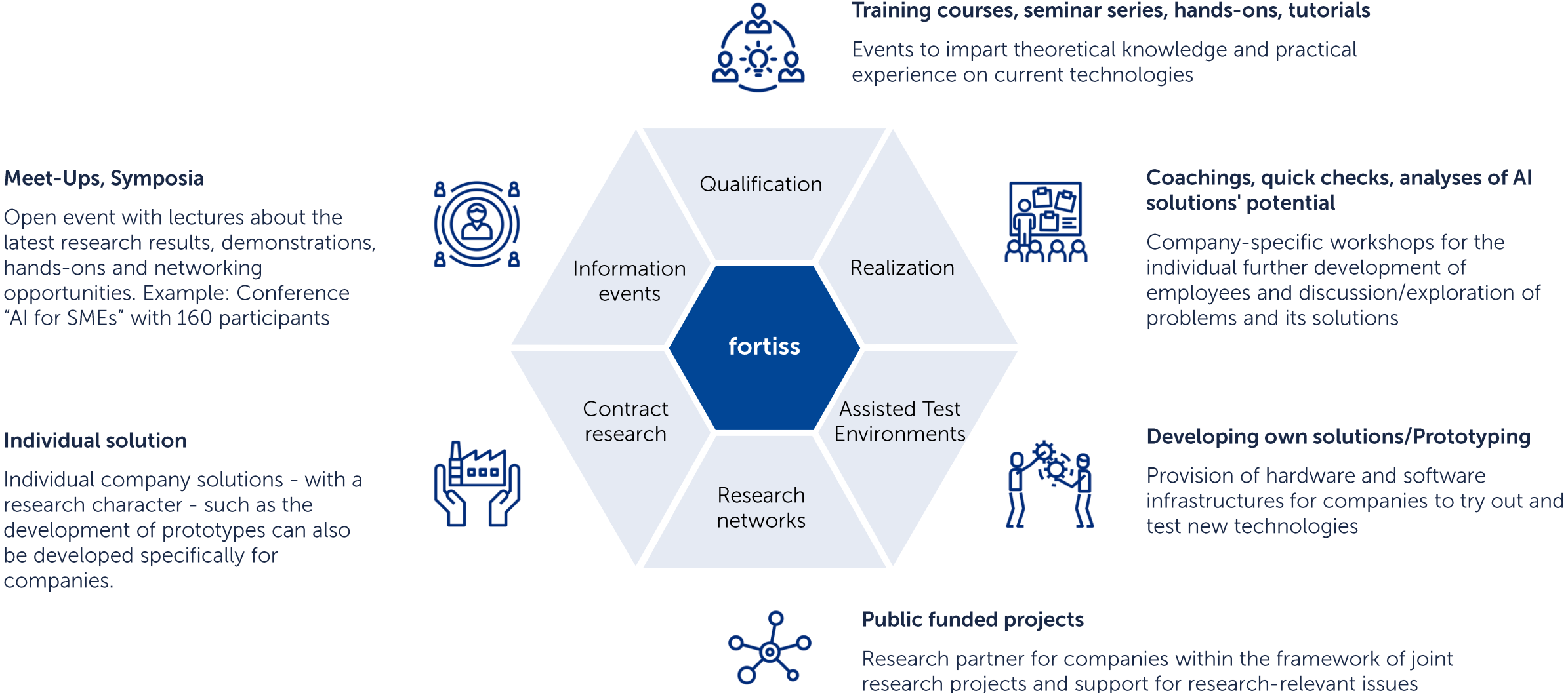


150

current
research partners

AI-related services of fortiss

Overview



Vision and mission

The DIH Munich provides AI-related services from exploration to business solution to foster digital expertise

Key AI expertise

Machine Learning

Deep learning, reinforcement learning

Reasoning & decision making

Planning/scheduling, search/optimization, knowledge representation

Robotics

Control, perception, sensors and actuators, integration in cyber-physical systems

Jointly operated by

fortiss

UNTER
NEHMER
TUM

MSRM
TUM

Key AI services

Consulting	Research networks
Start-Up creation and support	Partner platform activities
Qualification	Information events
Realization	Exchange & education
Assisted test environments	Engineering
Contract research	Analyses of AI solutions' potential

Robotics

- Natural human-robot interaction
- Intuitive instruction for users without expert knowledge in robotics
- Flexible production of small lot sizes
- Knowledge-based Digital Engineering
- Software & systems engineering for robotics



Research topics

From high-level reasoning to low-level control



Human-centric robot instruction

Robust recognition of human input through fusion of various input modalities

Intention recognition & dialog management

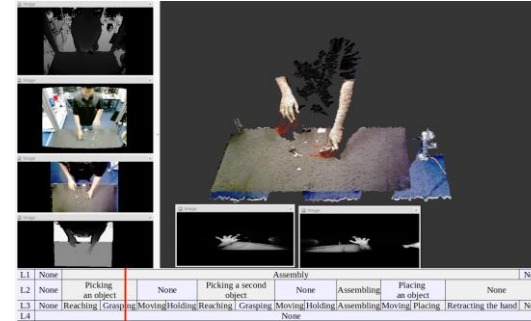
Social aspects of HRI



Semantic integration of heterogeneous engineering data

Linking of data for automatic generation of robot programs

Rich semantic context information of all aspects from design, engineering, and execution

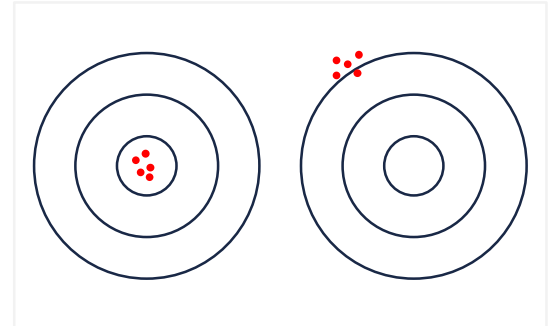


Integration of symbolic & subsymbolic AI techniques

Bridging the gap between different reasoning approaches

Plausibility checking on subsymbolic decision making

Leveraging symbolic models in subsymbolic learning



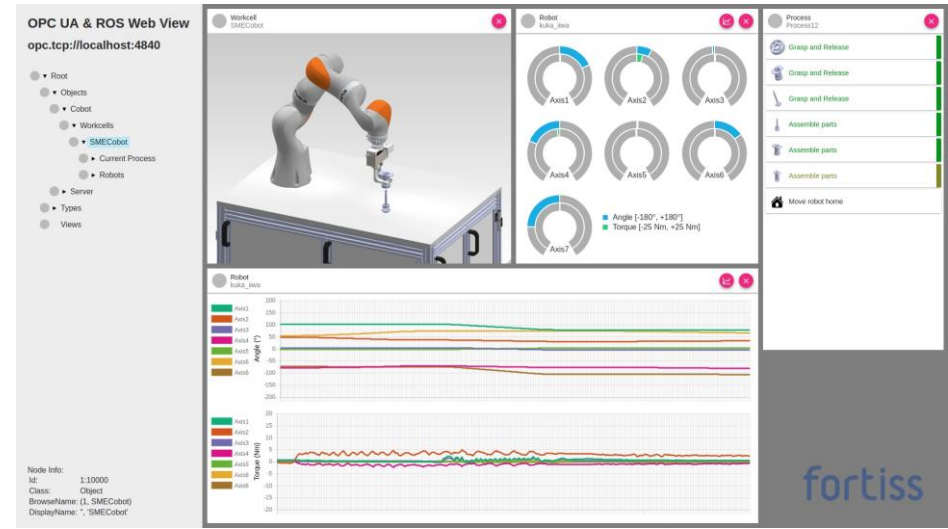
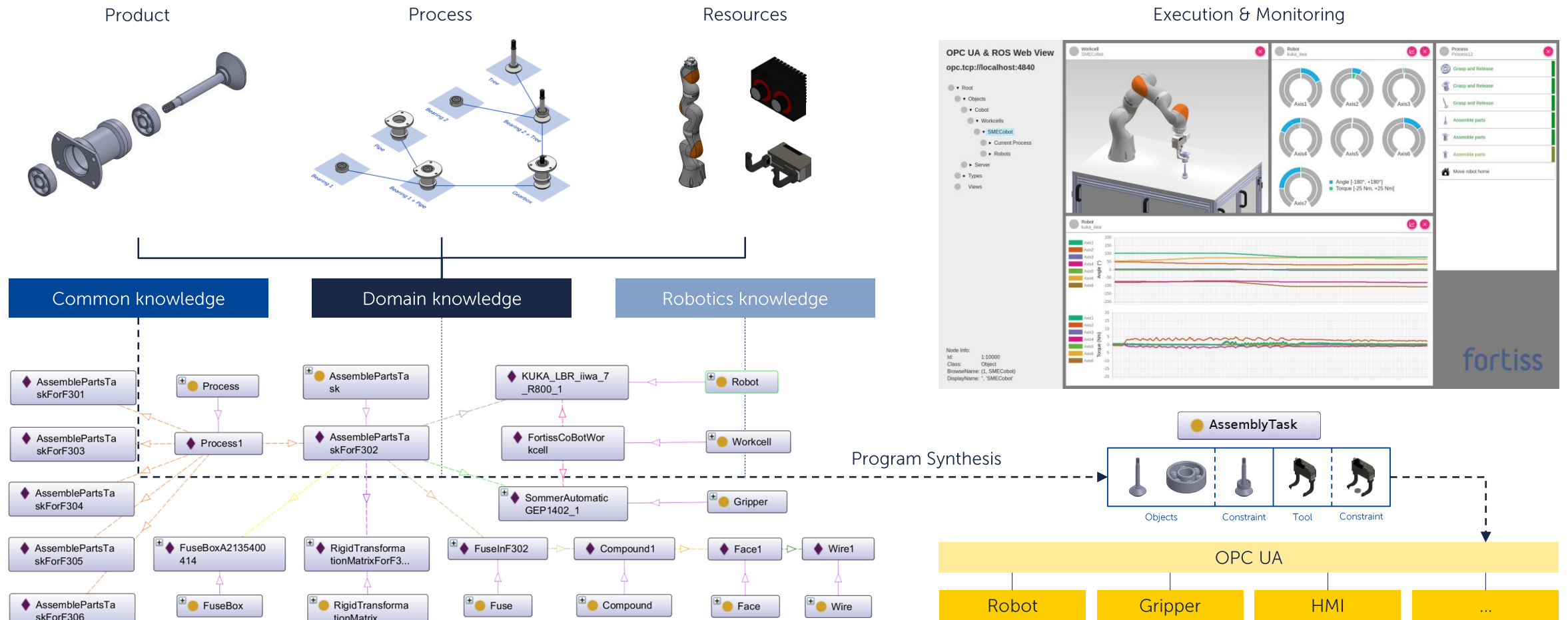
Generation of robust robotic control programs

Handling of uncertainty in product models, sensor signals, algorithms, and actuators

Unstructured and uncertain environments

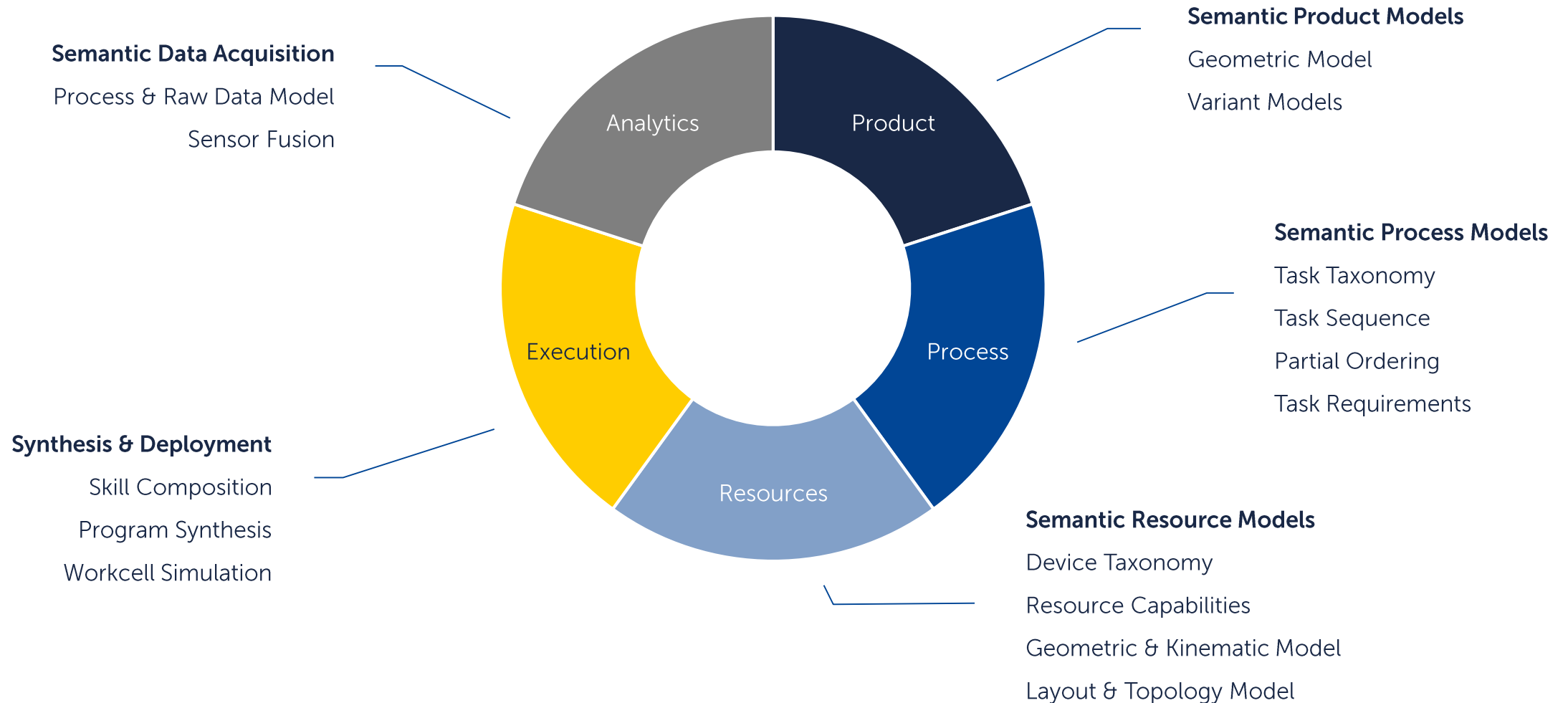
Example: Product-centric instruction of robots

Knowledge-based program synthesis for small lot production



Digital engineering

A model-driven development approach



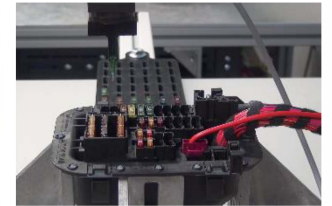
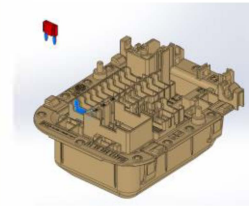
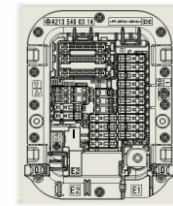
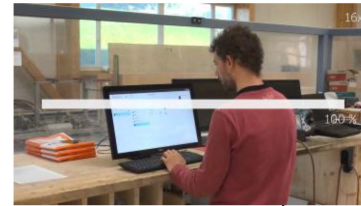
Applications & evaluation

Recent use cases

Gearbox assembly

Woodworking

Fuse insertion



	TeachPad	Intuitive
Programing of assembly task from scratch (4 parts)	48 min.	8 min.
Adaptation of object positions in existing program	23 min.	0 min.
Adaptation of process parameters (approach pose for 2 objects)	5 min.	2 min.

	TeachPad	Intuitive
Programing of process of wood domain from scratch (2 pick & place operations, 10 nailing lines, 4 sawing lines)	47 min.	14 min.
Adaptation of order of existing program	1.5 min.	0.2 min.

Project "Data Backbone" (ZD.B/StMWi Bavaria)
Partner: Lisa Dräxlmaier GmbH
Semantic integration of relevant data along value chain
Automatic generation of process models based on incoming orders and available knowledge
Automatic deployment, execution, and monitoring of modelled processes in automation workcells

What we are looking for

Project partners, end users, use cases

In particular for the following open calls and topics:

ICT-46-2020 (RIA)

- AI and Cognition
- Socially cooperative human-robot interaction
- Model-based design and configuration tools

ICT-46-2020 (IA)

- Agile production

ICT-47-2020

- Development of variable autonomy systems that significantly extend and enhance the operator's awareness of the working environment. Sharing autonomy between a human operator and a robot can speed up operations and raise productivity.

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