



Bavarian
Research Alliance

EU-Funding for Robotics- Research and Innovation



Dan Gutu

Scientific Officer
Information & Communication Technologies |
Engineering & Natural Science



Bavarian
Research and
Innovation Agency

Competent Support for Excellent Research in Bavaria, Europe and the World



Main Robotics-Calls in H2020

Various types of calls/topics: **RIA**, **IA**, **CSA** (according to funding and thematical area)

1. ICT-46-2020:

Robotics in Application Areas and Coordination & Support

- a) Research and Innovation Actions (RIA): Robotics Core Technology
- b) Innovation Actions (IA): Robotics for Agri-Food and Agile Production
- c) Coordination and Support Actions (CSA): Robotics

2. ICT-47-2020:

Research and Innovation boosting promising robotics applications (RIA)



Focus on Robotics-ICT in Horizon 2020

Topic-ID	Budget [Mio. €]	Expected funding
<u>ICT-46-2020: (RIA)</u> <u>Robotics in Application Areas and Coordination & Support</u>	41.5	6 - 7 projects, at least one per core technology
<u>ICT-46-2020: (IA)</u> <u>Robotics in Application Areas and Coordination & Support (IA)</u>	41.5	6 - 7 projects, at least 3 per application area
<u>ICT-46-2020: (CSA)</u> <u>Robotics in Application Areas and Coordination & Support</u>	3	1 project
<u>ICT-47-2020: (RIA)</u> <u>Research and Innovation boosting promising robotics applications</u>	20	7 – 10 projects



ICT-46-2020: Robotics in Application Areas and Coordination & Support

- RIA, IA & CSA
 - RIA: 41.5 Mio € / 6 - 7 Mio € per project, presumably 6 - 7 financed projects, at least one per core technology
 - IA: 41.5 Mio € / 6 – 7 Mio € per project, presumably 6 – 7 financed projects, at least 3 per application area
 - CSA: 3 Mio € / 3 Mio € per project, 1 financed project

- Deadline: April 22nd, 2020



- Address **technical and non-technical issues** in a **MODULAR** and **OPEN** way
 - „**open**“: not content, but **module interface**
 - **Proprietary components / software**, or connected to underlying proprietary software/hardware
 - **Interconnectable systems** deployed in demonstrators
- **Remove** (technical and non-technical) **barriers** that prevent a **widespread adoption of robots**:
 - safety, cybersecurity, privacy, ethical, legal, gender
- Consider user needs, societal and economic aspects



- **Increase autonomous capabilities** beyond SoA
- Prove and test through **pilot demonstrators** embedded in real / near-real environments
- **4 priority areas:**
 - healthcare,
 - inspection and maintenance of infrastructure,
 - agri-food,
 - agile production
- choose one of them



- Improve autonomy in **ONE** core technology (specify!):
 - AI & Cognition
 - Cognitive Mechatronics
 - Socially cooperative human-robot interaction
 - Model-based design and configuration tools
- Develop **core technologies (modular, open and non-proprietary) / toolkits** for deployable system platforms in **ONE** priority application area
 - (healthcare, inspection & maintenance of infrastructure, agri-food, agile production)
- Connect to running **Robotics DIHs** (DT-ICT-02-2018)
 - DIH HERO, RIMA, agROBO Food, DIH², Trinity



ICT46-RIA „Instructions“

- **Step change novelty**, not incremental advance
- **TRL3** and above, to be accurately accounted
- **Real impact** of the proposed technical advance
- **Lowering technical barriers** in prioritized application area
- Ressources for linking with DIHs



- Establish **large-scale pilots** to demonstrate the use of robotics in highly realistic environments
- Showcase advanced prototyping applications in **real or near-real environments**
- Demonstrate **high levels** of socio-economic impact
- **Two application areas** (choose one):
 - Agri-food from farming to processing and distribution
 - Agile production
- Define **platform interfaces** based on suitable reference architectures, to be rolled-out and evolve into **standards**



Large-scale pilots shall:

- Use **existing infrastructures**
- Develop **scalable technical solutions**
- Establish **strong collaborations** for innovative robotics applications in industry
- Develop **metrics for performance**
- Address **technical and non-technical issues**: socio-economic impact, novel business models, legal and regulatory, ethical and cybersecurity



ICT46-IA „Instructions“

- Clear linkage to running **Robotics DIHs**
- Potential for **impact at scale** in the chosen application area
- Sufficient capacity to **construct, deploy and disseminate the pilot**
- **Sustainability beyond funding**



- Support actions that develop **awareness and knowledge transfer**
- Address issues concerning the **entire robotics community**
- Develop **high-level stakeholder forum & communication strategy**
- **Legal and societal issues** with respect to **AI-based robotics technology**
- **Dissemination** of best practice to robotics stakeholders



ICT46-CSA „Instructions“

- Strategic engagement with stakeholders
- **Robotics as mission critical part of the AI strategy**
- Explore economic and strategic impact of robotics in multiple sectors



ICT47-2020: Research and Innovation boosting promising robotics applications

- RIA: 20 Mio € / 2 - 3 Mio € per project, presumably 7 - 10 financed projects
- Deadline: April 22nd, 2020



ICT47 Challenge

- **Enhance capabilities of robots** by exploring and developing opportunities from **novel technical developments** with respect to **physical intelligence**
- **Physical intelligence** from **combinations of underlying functional capabilities** developed beyond state of the art



ICT47 Scope

- **Innovative approaches to hard research problems**
- **Substantially improved solutions to challenging technical issues**
- **Open to all application areas**
- **Demonstration of potential for take-up in the selected application**
- **Applications with high socio-economic impact and low environmental footprint**

ICT47 Scope



Research areas:

- Autonomous micro- or millimeter scale robots
- Novel materials for service robotics
- Beyond human manipulation of objects
- Non-visual sensing novel for service robotics
- Intrinsically safe physical powerful robotic systems
- Variable/shared autonomy systems



- **Step change improvements** in technical performance from novel approaches (driven by a clear understanding of the SoA)
- **Technical developments** that open new markets or application opportunities
- Well established **demonstrators of the improved performance** within **sufficiently realistic operating environments**
- Link with **running robotics DIHs**
- **TRL4** demos



ICT47 „Instructions“

- **Unique solutions** that may cross discipline boundaries
- Balance of **technology capability** and **application awareness**
- Clear plan to construct **application relevant demonstrators**
- Plan for **engagement with DIHs** and other platforms



THANK YOU FOR YOUR ATTENTION!

Bavarian Research Alliance GmbH @ Bavarian Research and Innovation Agency

www.bayfor.org

www.bayfia.de

Headquarters in Munich



Prinzregentenstraße 52
80538 Munich
Germany

Dan Gutu
Scientific Officer ICT | Space

Phone: +49 (0)89 99 01 888-136
E-mail: gutu@bayfor.org
Internet: www.bayfor.org

Photo: © Bavarian Research Foundation,
Christine Reeb

Quaters in Nürnberg

Am Tullnaupark 8
D-90402 Nürnberg

Tel.: +49 (0)911 507 15-900
E-Mail: info@bayfor.org
Internet: www.bayfor.org